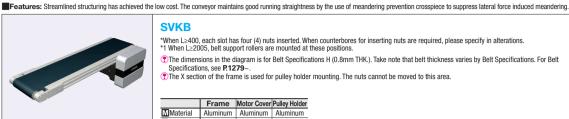


With Meandering Prevention Crosspiece, Head Drive, 2-Groove Frame (Pulley Dia. 30mm)

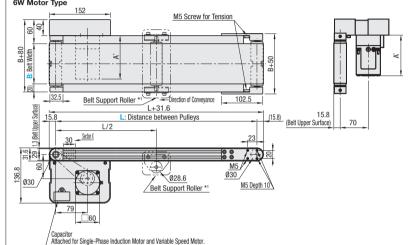


*When L≥400, each slot has four (4) nuts inserted. When counterbores for inserting nuts are required, please specify in alterations.

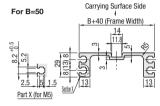
The dimensions in the diagram is for Belt Specifications H (0.8mm THK.). Take note that belt thickness varies by Belt Specifications. For Belt Specifications, see P.1279~.

The X section of the frame is used for pulley holder mounting. The nuts cannot be moved to this area.

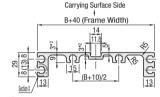
	Frame	Motor Cover	Pulley Holder
MMaterial	Aluminum	Aluminum	Aluminum
50 (5)	0		



Frame Cross Section and Enlarged View (Symmetrical

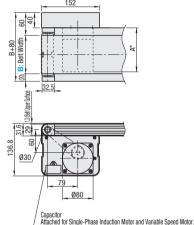


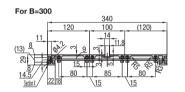
For B=100~250

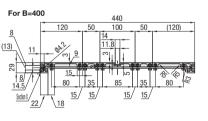


● For B=50, down facing slot is not provided.
 ● For B=200 and 250, *2 section thickness is 4mm.
 ● Compatible with JIS standard hex nuts.
 ④ A pre-assembly insertion nut is not included.



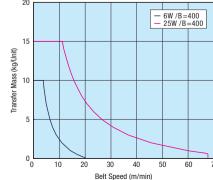






* A Dimension Details ■Conveying Capacity

				A
(W)	Specification	Manufacturer	Ratio	A
		Panasonic	5~25	101.0
		Fallasollic	30~180	108.0
	Induction Motor	Oriental	5~25	105.0
	IIIuuctioii Wotoi	Ulicital	30~180	115.0
6W		Taiwanese	5~75	120.0
OW		idiwaliese	90~180	127.0
		Oriental	5~25	115.0
	Variable Speed	Unentai	30~180	125.0
	Motor	Taiwanese	5~75	127.4
		idiwaliese	90~180	134.4
		Panasonic	5~180	115.0
		Oriental	5~18	117.0
	Induction Motor	Ulicital	25~180	127.5
		Taiwanese	5~75	129.3
25W		idiwaliese	90~180	136.3
		Oriental	5~18	127.0
	Variable Speed	Unental	25~180	137.5
	Motor	Taiwanese	5~75	140.0
		Idiwallese	90~180	147.0



*Reference Value may different by selected Belt.

■Gearhead Reduction Ratio

*Conveyance speeds are reference values based on IM (motor rotational speed 1,500 rpm [50 Hz]/1,800 rpm [60 Hz]). *May decrease depending on load condition.

Gearhead	Belt Spee	d (m/min)						
Reduction Ratio	50Hz	60Hz						
5	56.4	67.7						
7.5	37.6	45.1						
9	31.3	37.6						
12.5	22.6	27.1						
15	18.8	22.6						
18	15.7	18.8						
25	11.3	13.5						
30	9.4	11.3						
36	7.8	9.4						
50	5.6	6.8						
60	4.7	5.6						
75	3.8	4.5						
90	3.1	3.8						
100	2.8	3.4						
120	2.4	2.8						
150	1.9	2.3						
180	1.6	1.9						
© For motor enecification SCM, this is adjustable up to								

For motor specification SCM, this is adjustable up to $(1/15) \times (max. speed)$ The weight that can be conveyed decreases as the

Part	В	L			Motor			Motor Manufacturer Selection	
Number	Selection	5mm Increment	Output (W)	Voltage (V)	Specification	Gearhead Reduction Ratio	Belt Specification	The prices vary by manufacturer.	
SVKB	50 100 150 200 250 300 400 ⊗When B = 300 or 400,	300~3000	6 25 25	TA115 (Single-phase) SA220 (3-Phase) SA230 (3-Phase)	(Induction Motor) SCM (Variable Speed Motor) IM (Induction Motor)	5 7.5 9 12.5 15 18 25 30 36 50 60 75 90 100 120 150 180 S5~9 not applicable for 6W Motor	H (General Specifications, Green) W (General Specifications, White) G (For Sliding, Green) S (For Sliding, White) D (For Electronic Parts Transfer) O (0ll Resistant, Nary Blue) N (Non-adhesive, White) J No Belth		
	Output = 6W and Gearhead Reduction Ratio = 12.5~30 are disabled.		6 25	NV (No Motor)	NM (No Motor)	NH (No Gearhead)	*For belts other than the above, select from Belt Specification below.	R (No Motor, Gearhead)	

Connect the motor so that the belt rotates in the direction of conveyance. For connection diagram, and details of motor and inverter, see 🗷 P. 1267 onward.

When "No motor, gearhead" is selected, the motor mounting hole pitch will vary depending on the motor's power rating. Please see Technical Information in our Conveyor Selection web site for the dimension details.

When "No motor, gearhead" is selected, this unit will be delivered unassembled. The customer is to assemble the unit according to the included assembly instructions. See our Convevor Selection site for assembly procedures and packaging details.

Note that warpage might occur in belts with meandering prevention crosspiece depending on the number of plies (thickness). The state of the belt specifications.

~	,			
Belt Specification	Standard Belt (Body Price Only)	Optional Belt 1	Optional Belt 2	No Belt
General Purpose	H (Green), W (White)	-	-	
For Sliding	G (Green), S (White)	-	-	
For Inclined Transfer	-	-	-	
Grip Type	-	-	GG (Green), GW (White)	
Oil Resistant	(Green)	OW (White)	-	(No Belt)
Non-adhesive	N (White)	NB (Sky Blue), NBG (Lime Green) HH (Green), HW (White)	-	
For Food Transfer	-	KW (White), KSB (Sky Blue), PHB (Sky Blue)	-	
For Electronic Parts Transfer	D (Black)	-	-	

For flat belt details, see 🗷 P.1279 onward.

© lin case of selectiong Optional Belts, please select motor manufacturer A or B (Motor C is applicable for Standard Belt only.)

• Select a belt with a thickness of 1.0 mm or less for a motor output of 6 W.

Part			Body Price 1 ~ 2 pc(s).																				
Number	В	L300 ~400	L405 ~500	L505 ~600	L605 ~700	L705 ~800	L805 ~900	L905 ~1000	L1005 ~1100	L1105 ~1200	L1205 ~1300	L1305 ~1400	L1405 ~1500	L1505 ~1600	L1605 ~1700	L1705 ~1800	L1805 ~1900	L1905 ~2000	L2005 ~2200	L2205 ~2400	L2405 ~2600	L2605 ~2800	L2805 ~3000
	50																						
	100																						
	150																						
SVKB	200	-																					
	250	-	-																				
	300	-	-	-																			
	400	-	-	-	-																		

Pror orders larger than indicated quantity, please check with WOS.

Ex.) For No Belt Ex.) For Optional Belt 2 Ex.) For No Motor, Gearhead

	Motor Output	Specification	A (Panasonic Motor)	B (Oriental Motor)	C (Taiwanese Motor)	R (No Motor, Gearhead)
Motor Spec. Price	6W	IM				
	25W	SCM				

Belt	Standard Belt	Optional Belt 1	Optional Belt 2	No Belt
Spec. Price				





Motor Manufacture Selection

SVKB-100-1000-25-T100-SCM-25-J-B SVKB-100-1000-25-T100-SCM-25-HY-B SVKB-100-1000-25-NV-NM-NH-H-R

→ Body Price + Motor, Belt Spec. Price = Unit Price

Machine Weight (With a Motor Output of 6 W)

*Reference values (may vary depending on motor manufacture Belt Width Distance Between Pulleys L (mm)												
											B (mm)	500
	50	3.7	4.8	5.8	6.9	7.9	9					
	100	4.4	5.8	7.3	8.7	10.4	11.8					
	150	5	6.8	8.7	10.5	12.8	14.6					
	200	5.7	7.9	10.1	12.3	15.1	17.3					
	250	6.3	8.9	11.6	14.3	17.3	20					
	300	6.8	10.5	11.9	16	19	22.1					
	400	8.2	12.4	15	19.7	23.9	27.7					

*When the motor output is 25 W, add 1.1 kg.



Motor Position Reversed **Additional Counterbores Motor Cover with Window** Brackets for Speed Controller Included Post-Assembly Insertion Nuts Included Motor with Terminal Box

Stands (Legs) For details of alterations, see ZEP. 1264 onward.